

Design and Analysis of Axial Flux Permanent Magnet Generator for Low Wind Power Application

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Abstract—An axial flux permanent magnet (AFPM) machine with single rotor and single air-cored stator is studied in this project. An improved design of an ironless axial flux permanent magnet synchronous generator (AFPMSG) is presented for direct-coupled wind turbine application. The design for a low-speed, direct-drive, axial flux permanent magnet (AFPM) generator with a coreless stator and rotor that is intended for application to small wind turbine power generation systems. The main focus of this study is to improve the power output and efficiency of wind power generation by investigating the electromagnetic and structural features of a coreless AFPM generator. The design is validated by comparing the performance achieved with a prototype. The results of our comparison demonstrate that the proposed generator has a number of advantages such as a simpler structure, higher efficiency over a wide range of operating speeds, higher energy yield, lighter weight and better power utilization than conventional machines. The design and manufacturing processes for coreless axial flux permanent magnet generators are described for low cost rural electrification applications, where local production of small wind turbines is considered. Finally, a prototype machine is fabricated, and experiments are carried out to test its performances by comparing with design topology.

IndexTerms—AFPM, AFPMSG.

I. INTRODUCTION

Since generation of electricity is becoming very important and sensitive issue day by day. As we know wind energy is one of the cleanest, free and cheapest forms of energy. Wind energy is playing a vital role in generation of electricity, mostly in small scale residential or rural areas where electricity is not easily reachable. So the selection of economical and efficient wind generator is become very important topic for research now a days. Therefore many literatures were published on design and analysis of Axial Flux Machines (AFMs).The diverse studies shows that AFMs are become very attractive and cost effective alternatives for Radial Flux machines (RFMs) especially for applications such as small wind power system, aircrafts, compact engine generator sets, hybrid electric vehicles and direct battery charging.

Axial Flux Permanent Magnet (AFPM) machine size and shape are important features in applications where space is limited, so compatibility is crucial. Since PM machines are increasingly become very dominant machines with cost competitiveness of high energy PMs such as Neodymium Iron boron (Nd₂Fe₁₄).They are usually more efficient because of the fact that field excitation losses are eliminated resulting in significant rotor loss reduction. Hence the generator efficiency is improved and high power density is achieved. AFPM machines have no's of advantages over Radial Flux Permanent Magnet (RFPM) machines such as they have high power to weight ratio, high aspect ratio, reduced noise and vibration levels, adjustable air gaps and occupies less space etc., AFPM generators are most suitable than radial flux PM generators for small wind power applications.

In this report 200W, 16.66A and 719rpm Axial Flux Permanent Magnet (AFPM) generator's design and fabrication is discussed. Testing of AFPM generator is done in Electrical Machine laboratory, the result of the same are also included here. This report also includes various configurations of AFPM machines and comparison between them.

II. EXISTING SYSTEM WITH LIMITATIONS

Since there are no's of conventional PM generators are available for converting wind energy into electrical energy such as radial flux PM generators(synchronous or asynchronous, induction generators etc. But these conventional Radial Flux PM(RFPM) generators have no's of disadvantages as compared to AFPM generator such as they have low power density ,low torque, high cost, high cogging torque, less efficiency, fixed air gaps, high noise and vibration levels ,low torque to weight ratio and large in size etc.The slotted or non-slotted RFPM generators are also available .But the non-slotted RFPM generator has small aspect ratio (Diameter to length) results in high core losses. One advantage of this RFPM generator over AFPM generator is that they have better heat transfer.

III. VARIOUS TOPOLOGIES OF AFPM MACHINES

AFPM machines were first introduced in late 70s (Campbell, 1975)Growing interest in AFPM machines in several applications due to their high torque-to-weight ratio and efficiency as an alternative to conventional radial-flux machines was significant in the last decade. Axial flux machines are formed by a rotor disc produce an axial flux and a stator disc containing the phase windings. Many

variations in this basic design are possible, including single-sided, double-sided, torus, and multi-disc designs. Fig1. Shows various AFPM topologies.

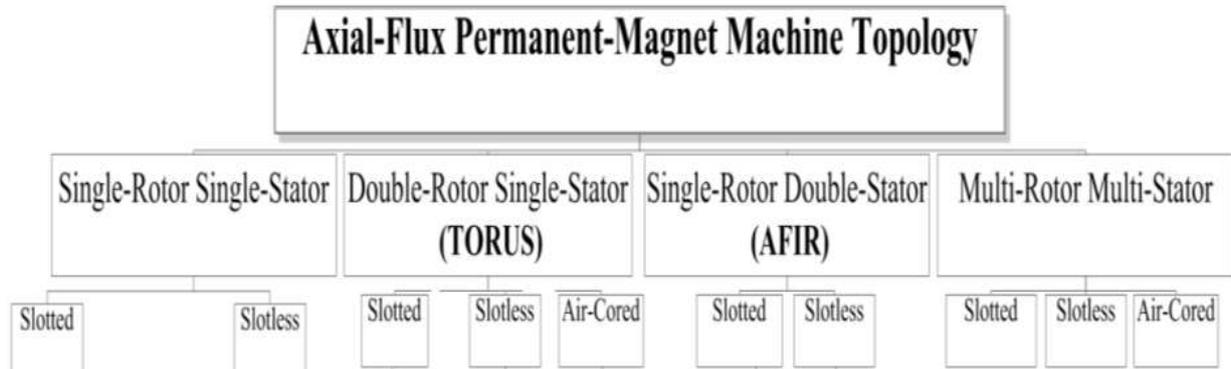


Fig. 1 various topologies of AFPM Machines

Proposed/selected topology

Fig 2 shows the simple and basic structure of AFPM Machines. Single stator and single rotor AFPM machine has a PM disc rotor mounted on the rotor surface and coreless stator winding immersed in epoxy resin. The magnetic force may twist the structure very easily. It is subject to unbalanced axial force between rotor and stator, so, does not like structures with balanced axial forces, it requires more-complex bearing arrangements and thicker rotor disk.

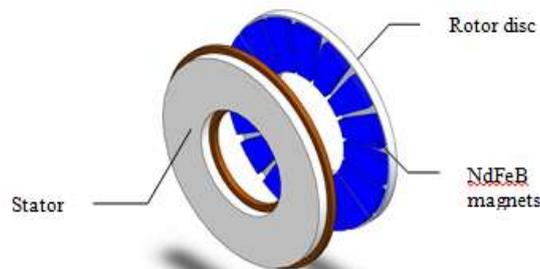


Fig. 2. Single stator single rotor AFPM topology

IV. BASIC OPERATING PRINCIPLE

- According to Faraday's law of electromagnetic induction, "Any change in the magnetic flux passing through coil, will induce a voltage in that coil".
- More rapid movement or stronger flux induces a higher voltage in each turn of each coil. The no. of coil turns, flux & rpm are factors on which the voltage produced by the coil depends.
- At low speed the coil will produce low voltage. When turbine reaches a certain cut-in speed, the voltage becomes nearly enough to charge a battery. Only when the speed is above the cut-in speed the stator feeds current into the battery.
- Generally the electrical output of the turbine will depend upon the strength of the wind and the size of the blades. The blades produce mechanical energy that is converted to electricity by alternator.

V. BASIC SELECTIONS

The manufacture of the generator that will meet the requirements requires careful selection of generator configuration, material and manufacturing methods. The materials were selected based on two major criteria: availability and cost. To fulfill these criteria often means that the generator efficiency has to be sacrificed. The following are the measures implemented to achieve economical cost:

How Big?

The amount of energy that you will get from the turbine depends mostly on the two things: The diameter of the blade rotor and the exposure to good winds. The power rating of the alternator in watts actually has very little influence most of the time, because full rated power is only available in stronger winds. The rest of the time the power is limited by wind and size & weight of rotor. I have decided to design AFPM for turbine diameter 1200mm, 12V and approximate power rating 30W.

Permanent magnets

The rare earth magnets, SmCo and NdFeB, have become popular because of their greater power density, high coercivity, high flux densities and the linearity of their demagnetization curves. NdFeB is preferred because it is cheaper and more readily available. Therefore, NdFeB magnets are selected for use in Permanent Magnet Generator (PMG), with some conservatively assumed values.

Stator & Rotor discs

One stator disc and one rotor disc is decided to use for making proposed AFPM generator. Stator disc is an assembly of coils emerged in epoxy resin and rotor is a magnet disc.

Material and Tool Selection

- All materials and tools used in the construction of generator need to be easily sourced and at low costs. Stator & rotor moulds are ideal for low cost application.
- These materials can be easily found anywhere in Maharashtra for exp. In Bhumi Enterprises in pune and wood workshops.
- Stainless steel disks need to be cut with plasma pantograph router are available in Shalimar Engineers, pune
- Bearing hub required for rotation of generator is a car or trailer hub which can be found in Proton Metal crafts Private Limited,Pune.
- Finally the neodymium magnets (NdFeB) which are the stronger magnets for less volume when compared to Ferro magnet are available JR Strong Magnet Pvt. Ltd,Pune
- Polyester resin is a material that can provide support for the stator coils which lay in the air and protection from corrosion for the magnets. It is available in Gayatree Polymers Private Limited, Pune.

VI. CONSTRUCTION OF AFPM GENERATOR

- The alternator is very simple. The magnets are mounted (glued) on steel disk. The magnets are arranged in N-S-N-S manner. The poles of magnets are their larges faces. The steel disk behind them completes the magnetic circuit between the back poles of magnets. Fig 3. Shows the rotor disk.



Fig.3 Rotor Disk

- The stator is the name for assembly of coils. Fig 4.shows the assembly of coils. One coil is made by winding 76 turns of enameled copper wire.



Fig.4 Assembly of coils

- When coils are connected together, they are placed in a mould and cast in polyester or vinyl ester resin as shown in Fig.5.



Fig.5 Stator cast in epoxy resin

- The stator and rotor are then mounted on shaft in such a way that they face each other, so that the magnetic flux from each magnet passes through each coil.

VII. BLOCK DIAGRAM OF AFPM GENERATOR

Fig. 6 shows block diagram representation of AFPM generator, as we can see we can rectify the output voltage of generator to charge the battery. Further we can use bridge inverter to achieve AC voltage, and then we can increase the voltage magnitude by using step up transformer.

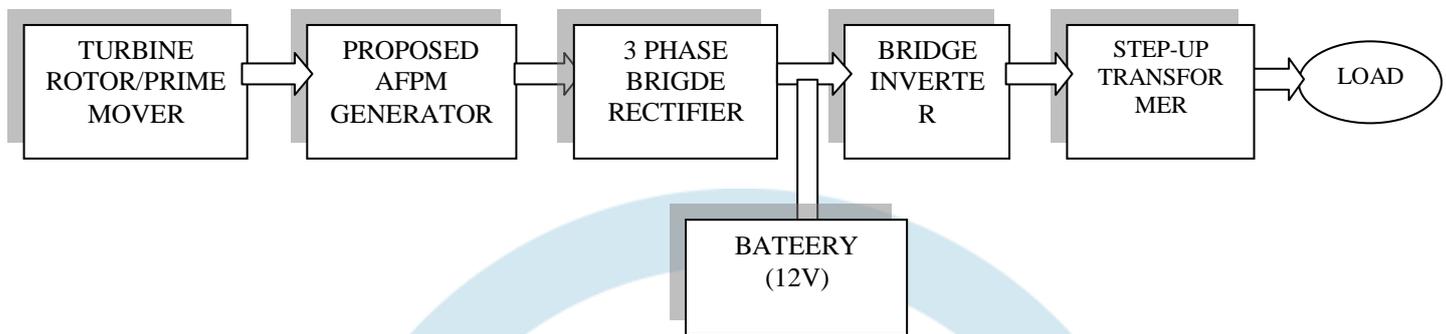


Fig.6. Block diagram representation of AFPM generator

Literature Survey

Wind power, considered as one of the cleanest renewable energies, is now receiving more and more attention. In some developing countries like China, with the supportive policies of the government, the utility of wind power is growing fast. Many wind power stations with large scale wind turbines have been built to provide electricity to the grid in places with good wind resources. However, in some remote but windy areas where grid is not available, small low-speed stand-alone high-efficiency wind generators can be very attractive for household electrical appliance as well as outdoor monitor equipments. So the selection of economical and efficient wind generator is become very important topic for research now a days. Therefore many literatures were published on design and analysis of Axial Flux Machines (AFMs). The diverse studies shows that AFMs are become very attractive and cost effective alternatives for Radial Flux machines (RFMs) especially for applications such as small wind power system, aircrafts, compact engine generator sets, hybrid electric vehicles and direct battery charging. The authors described different axial gap permanent magnet generators are designed and compared for one of the Caterpillar truck applications. Various axial gap designs with multiple stators and rotors are carried out and compared with a conventional PM generator in terms of torque density, efficiency, loss, heat dissipation, volume, inertia and weight. The results reveal the advantages of axial gap generators over radial gap generators and that internal rotor double stator disc generator fits the hybrid electric traction application with the given specifications.[1]

Design and manufacturing process for coreless axial flux permanent magnet generators are described for low cost rural electrification applications, where local production of small wind turbines is considered. The design was made using basic theoretical tools, simple programming methods, partially open source software, and simple manufacturing techniques.[2] The design, manufacturing process and performance results of a low cost permanent magnet generator for small wind application is described by author. Also mentioned that PM generators are able to achieve high efficiency compared with other generator types, but they also cost more than other generators. To make PM generators a low cost option, the generator configuration and materials have to be carefully selected. The authors described highlights on why the selected generator is designed, the choices made and the effect of used materials and manufacturing process on efficiency and energy yield. [3]

Axial flux permanent magnet machines today are important technology in many applications, where they are alternative to the radial flux permanent magnet machines. The review of the different topologies of axial flux permanent magnet generator and advances/trends in axial flux PM machines in aspect of construction, features, modeling, simulation, analysis and design procedure are described and analyzed with the help of 2D and 3D FEA tool.[4] The description of an axial flux permanent magnet (AFPM) machine with dual rotors and single air cored stator design is given in analytical form and the generator is applied for vertical shaft small power off grid wind generating system. A 1KW, 300 rpm, air cored outer rotor surface mounted AFPM is designed and analyzed. A 2-dimensional (2D) finite element analysis (FEA) method with sufficient accuracy is proposed to solve magnetic field inside the AFPM generator. This method simplifies the modeling and reduces the time of computation. Besides, analytical method is also presented to compute the air gap flux density (or magnetic field) of the generator.[5]

Since the Small-scale wind power applications require a cost effective and mechanically simple generator in order to be a reliable energy source. For such applications, characterized by low speed of rotation, the axial flux permanent magnet generator is particularly suited, since it can be designed with a large pole number and high torque density. The work on an axial flux permanent magnet synchronous generator, double sided with internal rotor and slotted stators is done by the authors. Such a structure gives a good compromise between performance characteristics and feasibility of construction. The design process of the machine is described and validated by test experiments. [7-8] The complete details of how to build six different sizes of Axial flux permanent magnet wind generator choosing between four or more voltages is described by the author in detail. Since everything such as how to make assumptions, approximately which size can produce how much power and voltage, manufacturing process of all AFPM generators, their installation and design procedure is described in detail with the help of mathematical formulas by the author. [9]

The authors mentioned the study of the magnetic field distribution in a two-rotor, permanent magnet, and ironless stator axial field generator for direct-drive wind energy conversion.[10] This generator uses trapezoidal shaped magnets rather than circular magnets

which allows the active area of the generator to be decoupled from its diameter, allowing a more compact machine to be built. A spreadsheet design procedure has been developed. The authors also described how this generator can be used to control turbine speed in strong winds. This is achieved by introducing an additional resistive dump load on the electrical output of the generator. Simulation of this strategy has also shown [11] Axial-flux permanent-magnet machines today are important technology in many applications, where they are an alternative to radial-flux permanent-magnet machines. [12]

Because the efficiency of the machine is important, specific measures are taken in order to reduce losses in the machine: thin laminated grain oriented material in the teeth, concentrated pole windings, and segmented magnets. [13] The performance of a coreless stator axial flux permanent magnet generator is calculated by using hybrid method which uses combination of finite element analysis (FEA) and theoretical analysis.

AFPM Generator design

In this paper the design of single stator single rotor AFPM generator is done mathematically. For designing the generator some assumptions are made first and then start designing the generator step by step. Following is the procedure of design.

I. CHOOSE WHAT TO DO/ ASSUMPTIONS:

Following table shows the parameters which were assumed and used in the design calculations of AFPM generator:
Table 1) Assumptions Made

Sr.no.	Parameter	Considered Value
1	Turbine Diameter(T_d)	1200mm
2	Power rating	200w
3	Tip speed ratio(λ)	6.25
4	Cut-in wind speed(V_w cut-in)	3 m/s
5	rated wind speed (V_w rated)	11.45 m/s
6	Power coefficient (C_p)	0.35
7	Application /load	Battery Charging(12V)
8	No. of phases	Three phase
9	Frequency(F)	20 Hz
10	Coil Fill factor(K_f)	0.55
11	Saturation coefficient(k_{sat})	1
12	Vacuum Permeability(μ_0)	$4\pi \times 10^{-7}$
13	Generator Topology	single stator(coreless)single rotor (steel disk)
14	Rectifier	Three phase bridge rectifier
15	Stator Outer diameter(S_{do})	293 mm
16	Stator Inner Diameter(S_{di})	85 mm
17	Rotor outer diameter(R_{do})	293 mm
18	rotor inner diameter(R_{di})	112 mm
19	purpose	for M.E. Project
20	Input device/prime mover	high speed AC cooler motor with blue common(200w,1500 rpm)
21	testing parameters	Speed & voltage
22	testing location	In college machine laboratory

The above assumptions are made by taking reference of various design literatures published before. Again following two assumptions were used for the design calculations:

- 1) The magnetic flux density crosses the air gap perpendicularly.
- 2) The effects of space harmonics of the magnetic flux density distribution in the air gap are neglected; only the fundamental is considered to contribute to power.

II. DESIGN CALCULATIONS:

Calculating the Blade/ Turbine rotor RPM (N):

The blade rotor speed is calculated by using following formula,

$$N_{cut-in} = \frac{(\lambda * V_w \text{ cut-in} * 60)}{(T_d * 3.1415)}$$

$$N_{\text{cut-in}} = \frac{(6.25 * 3 * 60)}{(1.2 * 3.1415)}$$

$$N_{\text{cut-in}} = 298.42 \text{ rpm}$$

Approximately 300 rpm is considered to design generator.

Aerodynamic power/Blade power (W):

Theoretical power contained in the wind is calculated as

$$P_{\text{air}} = \frac{1}{2} * \rho * A * V^3$$

Where ρ = air density at sea level = 1.225 kg/m³ (constant)

A = Swept area

$$A = \pi r^2$$

$$= 3.1415 * \left(\frac{Td}{2}\right)^2$$

$$= 3.1415 * \left(\frac{1.2}{2}\right)^2$$

$$= 1.1309 \text{ m}^2$$

We are calculating P_{air} for cut-in wind speed, Hence

$$P_{\text{air}}(\text{cut-in}) = \frac{1}{2} * 1.225 * 1.1309 * 3^3 = 18.7022 \text{ W}$$

Maximum power coefficient ($C_{p\text{max}}$):

However it is not physically possible to catch all of the wind and in reality the mechanical power that blades can produce is certain percentage of this, known as coefficient of performance (C_p). The highest possible C_p is 59.3% according to Betz limit, but for the proposed tip speed ratio the C_p is taken 40% as shown in below graph.

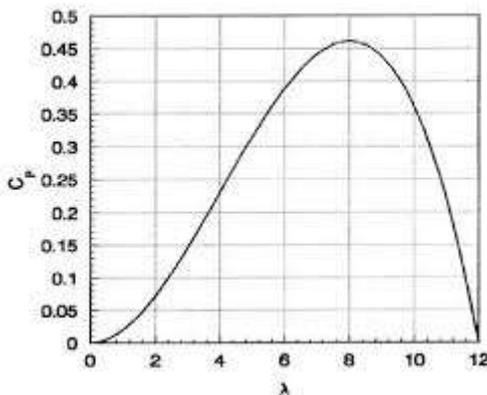


Fig 7. C_p vs λ graph

$$\begin{aligned} \text{Actual } P_{\text{air}}(\text{cut-in}) &= \frac{1}{2} * \rho * A * V^3 * C_p \\ &= 18.7022 * 0.40 \\ &= 7.4808 \text{ W} \end{aligned}$$

Calculation of output voltage and Speed:

The output voltage of generator is the function of rpm. According to the Faraday's law of electromagnetic induction the voltage induced in a wire depends upon the rate of change of magnetic flux through a coil. In each revolution flux cuts the coil twice: once entering a coil and once leaving.

$$\text{So the average voltage } (V_{\text{avg}}) = 2 * \phi_T * N_{\text{phase}} * \text{RPS}$$

Where

A) Total flux ϕ_T = Total Area of magnet (A) * Flux density near the magnet surface (B_{mg})

The flux density depends upon the way the magnets are used. If there are two magnet disks, then B_{mg} is about half of the remanent flux density (B_r) of the magnet. The magnets selected are of size ($l_m * W_m * H_m$) = (50 mm * 25 mm * 12.5 mm), NdFeB type and grade N35. Its remanent flux density is 1.21 T.

Now, Flux density near the magnet surface (B_{mg}) = $\frac{B_r}{2}$
 $= \frac{1.21}{2} = 0.605$ See the turbine going to design is too smaller in diameter as well as it has only one magnet disk and have lower flux density. So practically it is assumed as 0.3T for this case.

So let us take $B_{\text{mg}} = 0.3\text{T}$

$$\begin{aligned} \text{Area of one magnet (A)} &= l_m * W_m \\ &= (50 * 10^{-3}) * (25 * 10^{-3}) \\ &= 0.00125 \text{ m}^2 \end{aligned}$$

$$\text{no. of poles/magnets (P)} = \frac{(120 * F)}{(N)}$$

$$\frac{(120*20)}{(300)}$$

$$P = 8$$

Since there are eight magnets, then to achieve total area of magnet we can use following formula

$$\text{Total magnet area (A)} = \text{Area of one magnet} * \text{total no. of magnets (P)}$$

$$= 0.00125 * 8$$

$$= 0.01 \text{ m}^2$$

$$\text{Total flux } \phi_T = \text{Total magnet area (A)} * \text{Flux density near the magnet surface (Bmg)}$$

$$= 0.01 * 0.3$$

$$= 0.003 \text{ wb/m}^2$$

B) Total no. of turns /phase (N_{phase}) = Total no. of turns /coil * total no. of coils per phase

Total no. of coils (Q) can be calculated as

$$\frac{2Q}{3P} = \alpha_i$$

Where α_i = Aspect ratio=0.5(assumed)

$$\frac{2Q}{3*8} = 0.5$$

$$Q = \frac{(0.5*3*8)}{(2)}$$

$$Q = 6$$

$$\text{No. of coils per phase (q)} = \frac{Q}{3} = 2$$

take total no. of turns per coil (N_c) = 76 (assumed)

$$\text{Total no. of turns /phase (N}_{\text{phase}}) = \text{Total no. of turns /coil} * \text{total no. of coils per phase}$$

$$= 76 * 2$$

$$= 152$$

$$\text{C) Revolutions per second} = \frac{\text{RPM}}{60}$$

$$= 5$$

$$\text{So the average voltage (V}_{\text{avg}}) = 2 * \phi_T * N_{\text{phase}} * \text{RPS}$$

$$= (2 * 0.003 * 152 * 5)$$

$$V_{\text{avg}} = 4.56 \text{ V}$$

$$\text{The three phase average voltage} = \sqrt{3} * V_{\text{avg}}$$

$$= 7.898 \text{ V}$$

$$\text{Peak } 3 \phi \text{ output voltage} = 1.57 * 7.89$$

$$= 12.39 \text{ V}$$

$$\text{RMS value of } 3 \phi \text{ output voltage} = \frac{12.39}{\sqrt{2}}$$

$$= 8.761 \text{ V}$$

If we want to charge battery, the above voltage is rectified through rectifier.

$$\text{Then, the DC output voltage} = 12.39 - 1.4$$

$$= 10.99 \text{ V}$$

Magnet- coil combination:

three coils for every four magnets.

Calculation of wire sizes and power loss:

It is always economical to choose largest wire size that fits the available space to minimize loss of power and heating of stator. Available space for copper depends upon size and thickness of stator. Coil fill factor between 55% to 60% seem to be typical with great care taken. In this case 55% fill factor is assumed.

a) Calculation of cross-section area of copper (S_c):

Cross section area of copper that you can fit into the coil can be calculated as:

$$S_c = \text{Coil leg width} * \text{Coil thickness} * \text{fill factor}$$

$$= w_c * t_w * k_f$$

Where Coil thickness (t_w):

The axial thickness of stator coils can be calculated by assuming that there is no magnetic flux leakage. The coreless machines would not normally be operated in the saturation condition.

So let us take $k_{\text{sat}} = 1$

Axial thickness of stator coils can be calculated as follows:

$$B_{mg} = \frac{Br}{1 + \mu_{rrec} \frac{(g+0.5tc)}{Hm}}_{ksat}$$

Where $\mu_{rrec} = \frac{Br}{\mu_0 Hc} = \text{Recoil permeability}$

$Hc = \text{Coercive field strength} = 915000 \text{ A/m}$

$\mu_0 = \text{Vacuum Permeability} = 4\pi * 10^{-7}$

$$\mu_{rrec} = \frac{1.21}{(4\pi * 10^{-7}) * (915000)}$$

$$= 1.0523$$

g = Mechanical clearance gap = Resin layer over stator coil + resin over magnets + distance between magnet face & coil

$$= 1 \text{ mm} + 1 \text{ mm} + 2 \text{ mm}$$

$$= 4 \text{ mm}$$

$$0.3 = \frac{1.21}{1 + 1.05 \frac{(4 + 0.5tc)}{12.5}}$$

$t_c = 10 \text{ mm}$

Assume coil leg width (w_c) = 23 mm

$$\begin{aligned} \text{Now, } S_c &= w_c * t_w * k_f \\ &= 23 * 10 * 0.55 \\ &= 126.5 \text{ mm}^2 \end{aligned}$$

Since there are 76 turns per coil, hence cross section area available for each copper wire = $\frac{126.5}{76} = 1.66 \text{ mm}^2$

As we know there are only certain sizes of wires are available, so it is always better to choose nearest one. Nearest one size chosen was 1.59 mm²

b) Diameter of single copper wire (d_c) = 1.42 mm

Standard wire guage (SWG) = 17.

c) Calculation of Resistance of coil (R_c):

The resistance of the coil is important for working out the performance of the alternator when it is producing current. Since we already assumed or know the thickness of the wire but now we need to calculate the length of wire. **Average length of a turn of wire (l_{Tavg})** can be calculate as

$$\begin{aligned} l_{Tavg} &= 2 * (l_m + W_m) + 3.14 * (w_c) \\ &= 2 * (50 + 25) + 3.14 * (23) \\ &= 222.22 \text{ mm} \end{aligned}$$

we can calculate **average length of the coil (l_{cavg})** as ,

$$\begin{aligned} (l_{cavg}) &= N_c * l_{Tavg} \\ &= 76 * 222.22 \\ &= 16888.72 \text{ mm} \end{aligned}$$

Weight of a single coil = $l_{cavg} * \text{area of a copper wire} * 0.009$

$$= 16888.72 * 1.59 * 0.009$$

$$= 0.241 \text{ kg}$$

Total weight of stator coils = $6 * 0.241$

$$= 1.45 \text{ kg}$$

We can calculate the resistance of coil as,

$$R_c = \rho \frac{l}{a}$$

Where $\rho = \text{Resistivity} = 1.72 * 10^{-8} \Omega\text{-m}$ (For annealed copper wire and at temperature coefficient 20⁰c)

$$R_c = (1.72 * 10^{-8}) * \frac{(16888.72 * 10^{-3})}{(1.59 * 10^{-6})}$$

$$= 0.182 \Omega$$

d) Calculation of Resistance of stator (R_s):

The simplified way to consider the current in the stator is to say that it uses two of the three wires at any given time, and passes through two phases in series. In fact there will be some sharing of current at times between all three wires. So we can estimate the stator resistance:

$$R_s = 2 * q * R_c$$

$$= 2 * 2 * 0.182$$

$$= 0.728$$

e) Calculation of current and power loss:

$$\text{Current (I)} = \frac{\text{Power}}{\text{Voltage}}$$

$$= \frac{200}{12}$$

$$= 16.66 \text{ A}$$

$$\text{Power loss} = I^2 * R_s$$

$$= (16.66)^2 * 0.728$$

$$= 202.06 \text{ W}$$

From the above calculations we can say that the blades will have to produce 402 W to cover the above losses.

Efficiency of generator (% η):

$$\% \eta = \frac{200}{402 + \text{Restifier losses}} * 100$$

$$= \frac{200}{402 + 23.32} * 100$$

$$= 47\%$$

Rated wind speed:

Knowing the power required to drive the alternator we can find out the windspeed needed.

As we know,

$$P_{air} = \frac{1}{2} * \rho * A * V^3 * C_p$$

$$V^3 = \frac{P_{air}}{\frac{1}{2} * \rho * A * C_p}$$

$$= \frac{425.32}{(\frac{1}{2} * 1.225 * 1.1309 * 0.40)}$$

$$V = 11.45 \text{ m/s}$$

Stator Cooling:

It is always helpful to work out the heat dissipation per square centimeter of stator surface so as to avoid burning the stator out. The resin is a poor conductor. Look out the places where the coil is near the surface. Exposed surface of a coil on each side is

$$\text{Surface} = 2 * w_c * l_{Tavg}$$

$$= 2 * (23 * 10^{-3}) * (222.22 * 10^{-3})$$

$$= 10.22 \text{ m}^2$$

$$= 102.22 \text{ cm}^2$$

Each coil will only be working 2/3 of the time according to our approximate analysis of current in the stator.

$$\text{Loss in each coil} = \frac{2}{3} * I^2 * R_c$$

$$= \frac{2}{3} * (16.66)^2 * 0.182$$

$$= 33.67 \text{ W}$$

$$\text{So heat dissipation in w/cm}^2 = \frac{33.67}{102.22}$$

$$= 0.329 \text{ W/cm}^2$$

Estimation of RPM :

We already calculated the cut –in speed, but it is always helpful to calculate the speed at which alternator will produce output power. The no load voltage is more or less proportional to rpm but the DC voltage is not exactly proportional to rpm because of rectifier loss. When the alternator is connected to battery its actual DC voltage is clamped to the battery voltage. The impedance of the stator is not same as its resistance. There is some self inductance that causes resistance too and rectifier makes this very difficult to analyze.

As per the rule of thumb we can achieve a rough idea of impedance by multiplying the resistance by 1.3.

$$\text{Approximately Impedance}(Z_s) = R_s * 1.3$$

$$= 0.728 * 1.3$$

$$= 0.946 \Omega$$

we can calculate the extra voltage required to drive the desired current as

$$\text{Extra voltage} = Z_s * I$$

$$= 0.946 * 16.66$$

$$= 16.28 \text{ V}$$

$$\text{Total voltage} = \text{Extra voltage} + \text{battery voltage}$$

$$= 16.28 + 12$$

$$= 28.28 \text{ V}$$

$$\text{Then RPM} = (\text{DCV} + 1.4) * \frac{11}{A * B * N_{\text{phase}}}$$

$$= (28.28 + 1.4) * \frac{11}{0.01 * 0.3 * 152}$$

$$= 719 \text{ Rpm}$$

III. SUMMARY OF DESIGN

Following table 2 and table 3 shows the summary of design calculation done above

Table 2) Electrical parameters summary

r.no.	Parameter	Calculated /Proposed design
1	Rotor type	steel disk (ss& magnets mounted)
2	Stator type	Assembly of coils(coreless ,Non-magnetic)
3	magnet type	Neodiamium Iron Boron earth magnets(NdFeB)

4	magnet Grade	N35
5	No. of magnets(poles) required	8 pieces
6	Magnet Diamentions(l x w xh)	50mm x 25 mm x 12.5mm
7	Magnet shape	Rectangular
8	wire	Enamelled copper wire
9	Total no. of copper coils	6
10	Coils per phase	2
11	Total wire weight	1.45 Kg
12	Crosssection area of a copper wire	1.66 mm ²
13	Copper wire Diameter	1.42 mm
14	SWG	17
15	No. of turns per coil	76
16	Length of one coil	16888.72 mm
17	Stator wiring connection	Star connection
18	Output wiring	three finish ends of star connection & a neutral
19	Stator mould	
	1)Material	Plywood(Rectangular Pieces)
	2)No.of plywood pieces	Three(Lead,base& surround)
	3)Lead(l x w x h)	340mm x 355mm x 11 mm
	4)base(l x w x h)	340mm x 355mm x 11 mm
	5)surround(l x w x h)	340mm x 355mm x 18 mm
20	Casting the stator	<ol style="list-style-type: none"> 1)Make the coil by using coil winder 2) Assemble the coils together 3) Fix the assembly into mould 4) Pure the epoxy resin and hardner into the mould 5) Let the resin get dry 6) Remove the coil assembly from mould
21	Casting the rotor	<ol style="list-style-type: none"> 1)Testing of magnets for achieveing N & S poles 2)Glue the magnets on the steel disk 3) Arrange them into N-S-N-S manner
22	Resin Casting	<ol style="list-style-type: none"> 1) take one small plastic tea cup and pure araldite epoxy resin in it 2)Take one small plastic tea cup & pure araldite hardner in it. 3) Mix both of them with help of spoon & stick 4) pure it on stator coils which are placed in stator mould 5) keep it for 1 day to get dry.
23	Alternator assembly & testing	<ol style="list-style-type: none"> 1)First take MS shaft 2)Then fix the MS flat patti which is welded to bearing at the base of shaft 3) Place the rotor mounted stell disc on the MS flat patti 4)Then take the casted stator & fix it with MS flat patti which is welded to bearing 5) Then Place the stator assembly on MS shaft above the rotor disk 6) Then put one rectangular shape plywood piece at the bottom for supporting whole alternator assembly 7) Then fix the stator assembly to the bottom placed plywood piece with the help of nuts,bolts and washers

	8) Then fix the prime mover at the top of stator to the MS shaft to rotate the rotor
	9) Then test the alternator in machine lab for required speed

Table 3) Alternator design summary

Sr. No	Design Parameters	Proposed /calculated design value
1	Cut- in rotor speed	300 rpm
2	Rated rotor speed	719 rpm
3	Blade/wind /rotor/turbine power (Pair cut-in)	18.7 W
4	Blade/wind /rotor/turbine power (Pair Rated)	237.58 W
5	Blade/wind /rotor/turbine power (Pair cut-in) according to Bits limit	7.48 W
6	Blade/wind /rotor/turbine power (Pair rated) according to Bits limit	95.03 W
7	Magnet Flux density(Br)	1.21T
8	Magnet flux density near magnet surface(Bmg)	0.3T
9	Total no. of magnets	8
10	Area of total magnets(A)	0.01 sq.m
11	Total flux	0.003 wb/sq.me
12	Magnet Coercive flux strength (H)	915000 A/m
13	Total no. of turns /coil	76
14	Total no. of turns /phase	152
15	Revolutions per second(rps)	5
16	Single phase average voltage(Vavg)	4.56 V
17	Three phase average voltage	7.89V
18	Three phase peak voltage	12.39V
19	Three phase RMS voltage	8.76 V
20	Approximate Rectifier losses	1.4V
21	DC output voltage	10.99V
22	One coil length	16888.72 mm
23	coil leg width	23 mm
24	Coil thickness	10mm
25	Recoil permeability	1.0523
26	Mechanical clearance gap between stator and rotor(g)	4 mm
27	cross section area of single copper wire (Sc)	1.66 sq.mm
28	Diameter of single copper wire (dc)	1.42 mm
29	Standard wire guage(SWG)	17
30	Resistance of one coil ®	0.182 Ω (at 20 degree)
31	Stator Resistance (Rs)	0.728 Ω
32	Rated current(I)	16.66 A
33	Power Losses/copper losses	202 W
34	Power losses due to rectifier	23.32 W
35	Efficiency(%)	48.02
36	Heat dissipation (Cq)	0.314 W/Sq.cm
37	Stator Impedance(Zs)	0.946 Ω

The design of AFPM generator is started with some assumptions which are mentioned in table 1 above. After that step by step design calculations are started. The mathematical or theoretical design is done with the consideration of wind turbine generator. That means the generator is designed for wind application. The wind speed is calculated in rpm by using wind turbine terminology

formulas ,but actually at student level it was not possible to place the wind turbine assembly, hence practically the designed generator is tested in college laboratory by using prime mover. All the required parameters for wind turbine design are calculated above. Finally the summary of design is mentioned in table 2 and 3.

Fabrication and Installation of AFPM Generator

I. FABRICATION

Tools Used:

In most cases there are various options depending upon cost and what skill you may have.

Table 4) Tools Used

Sr.No	Purpose	Tools Used
1	Safety	Hand gloves
		small square shape wooden parts
2	All purpose	screwdrivers
		spanner set
		cutter
		center punch
		Drill machine
3	For Marking & Measuring	Hammer
		Compass
		Pro-circle
		Black marker
		Pencil
		roller
4	Electrical	scale
		Multimeter
		Tachometer
		soldring gun
		Extention board
5	Mechanical	coil winder
		Nut bolts
		MS flat Patti (215mm x 25.4mm x 5mm)(for stator)
		MS flat Patti (160mm x 25.4mm x 5mm)(for base)
		Bush(bearing adapter)
		Washers
		MS Shaft
Bearings		
6	Resin Preparation	Araldite epoxy resin (1 kg)
		Araldite Hardener (800 g)
		spoons, two small use-n-throw tea cups and sticks for mixing resin &hardner

Auto-CAD drawing images of stator & rotor:

Stator: The following fig 8 is showing an auto-CAD image of Stator disc.

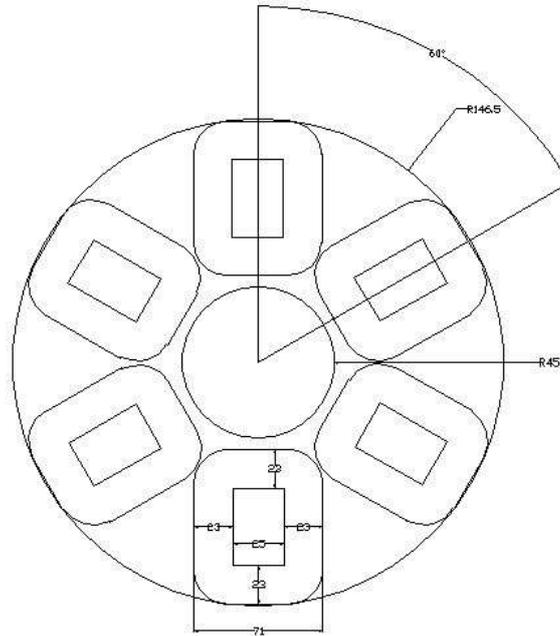


Fig.8 Auto-CAD image of stator

Rotor: The following fig 9 is showing an auto-CAD image of rotor disc.

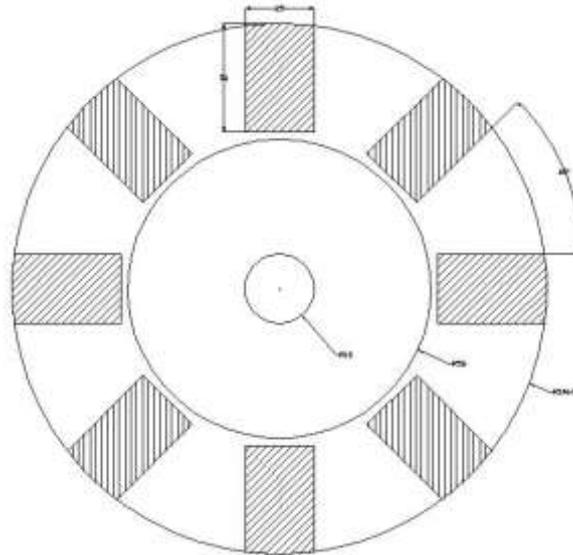


Fig.9 Auto-CAD image of rotor

Material Collection:

- Stator:**
- 1) Enamelled copper wire of gauge 1.42mm is brought from AanandElectricals, solapur. (Total copper wire weight 1.45 kg)
 - 2) Then prepare coil winder for winding the coil in college workshop.
 - 3) Then brought cotton tape for protection and having good mechanical strength of coil.
 - 4) Then brought Metal for soldering purpose.
 - 5) Then brought three rectangular plywood pieces namely lead, base & surround of size (340mm x 355mm x 11mm), (340mm x 355mm x 11mm) & (340mm x 355mm x 18mm) for preparing stator mould.
 - 6) Then ordered Araldite epoxy resin and hardener for casting the assembly of stator coils.
 - 7) Then prepare the MS flat Patti (215mm x 25.4mm x 5mm) in college workshop to place or support the stator on shaft

Rotor: 1) Purchase Stainless Steel (SS) disc then done the cutting of SS disc in required size.

2) After that purchase 8 rectangular pieces of NdFeB magnet from permagtradelink, wakdewadi, pune.

3) Then purchase Araldite glue and fevi quick for sticking the magnets on SS rotor disc.

Other: 1) Purchase two bearings, one for base and another for stator. Base bearing is of 6000 no. (Size) and rotor bearing is of 6001 no. (Size) from AanandElectricals, solapur.

2) Then brought ceiling fan shaft from AanandElectricals, solapur.

3) Purchase nuts, bolts and washers for mechanical arrangement of generator.

Manufacturing Process:

Following is the step by step procedure for manufacturing of AFPM generator:

1) First get Auto-CAD drawing of theoretically designed stator and rotor.

2) Then decided to fabricate stator initially, for that made the 6 coils of enamelled copper wire as shown in fig.10. Each coil is wound by cotton tape for achieving tightness and good mechanical strength.



Fig.10 copper coils

3) Then connected the 6 coils in series star connection as shown in fig.11.



Fig.11. star connection

4) After that testing of star connection or continuity is done with the help of lamp as shown in fig 12.



Fig.12. Testing of connection

5) Then took the SS rotor disc which was cut as per required size and start to divide the disc in 45° as shown in fig.13. And also mark the space for placing magnets.

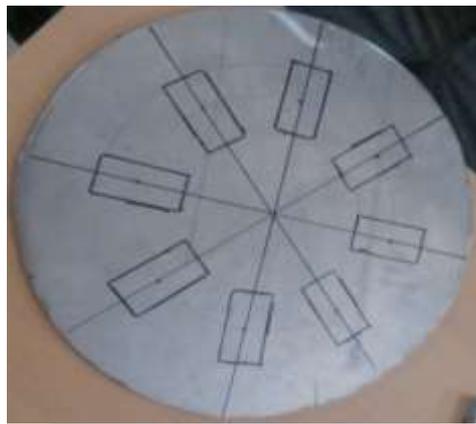


Fig.13. Rotor disc marking

6) Now started to place the magnets one by one on SS disc with the help of Araldite glue and fevi quick as shown in fig14. After all magnets glued the rotor disc is look as shown in fig.15.



Fig.14. Placement of magnet



Fig.15. Magnet rotor disc

7) Fixed the star connected assembly of coils on the plywood piece for testing the generator output and at the same time taken the marking on MS flat patti for drilling purpose as shown in fig.16



Fig.16. Marking on MS flat patti

8) Started to make holes in two MS flat pattis, for fixing the stator and rotor on the shaft with the help of drill machine in the workshop as shown in fig 17.



Fig.17. Drilling of MS flat patti

- 9) Took the SS magnet disc and fix the bush at the back side and in the center of the disc for smooth rotation of disc as shown in fig 18.



Fig 18. Rotor disc with bush

- 10) Then fix the base MS flat patti at the bottom bearing which is fixed with the shaft, then place the rotor disc on the shaft as shown in fig.19.



Fig.19. Placing Rotor on shaft

- 11) Done the testing of Generator output as shown in fig 20.



Fig.20 Testing of Generator output

- 12) Took the surround of plywood and cut it with the diameter which is quite greater than stator disc outer diameter. After that surround is put on base piece. Then assembly of star connected coils is placed into the hole in surround which is covered by news paper. After that araldite epoxy resin and hardener is mix in cup and pour on the assembly of coils placed into the surround until all coils are completely emerged into the resin as shown in fig 21.



Fig.21. Stator coils casted in epoxy resin

II. INSTALLATION:

Once the stator and rotor disc are ready, next step is to assemble or install them on shaft .In this case the shaft of ceiling fan, two bearings ,two MS flat patti and nuts-bolts are used to assemble stator and rotor disc .Installation procedure is explained below as a next step of manufacturing process :

1) Kept the above casting for one complete day to get it dry. After that make the holes in the casting to fix it to the MS flat patti as shown in fig 22 a) and b).



a) b)

Fig.22. a) Drilling of casted stator b) fixing MS flat Patti to casted stator

2) One bearing of 6000 no. is fixed at the base of the shaft and another bearing of 6001 no. is fixed at the top of rotor disc as shown in fig 23. Then placed stator disc on the shaft as shown in fig 24. And balanced mechanical distance between stator and rotor disc is maintained to 5mm. as shown in fig 25.



Fig.23 Fixing rotor



Fig.24 Fixing Stator



Fig.25 Adjustment of gap between stator and rotor

3) For making stator disc stationary, it is fixed to the base plywood rectangular piece as shown in fig 26. The three terminals R, Y, B and a neutral is brought out from the casted stator disc for testing and connection purpose. The rectangular plywood piece is fixed at the bottom of assembly for balancing the generator. The rubber black bush is fixed to the base plywood piece.



Fig.26 Rectangular Piece base

TESTING, RESULTS AND DISCUSSION

I. TESTING

Once the fabrication of AFPM Generator is finished, its testing is done in the college machine laboratory. Since it is not possible at student level to place a wind turbine for testing purpose hence the testing is done in college laboratory. So instead of using wind turbine to give mechanical input to generator, a prime mover having high torque and low speed is selected to give input to the generator. Such a prime mover is our drill machine which generally has high torque and low speed as per our requirement. Following Two tests are conducted on generator to check its performance:

A) No- load Test:

In this test generator is acting as open circuit i.e. load is not connected to its output as shown in fig 27. With the help of drill machine input is given to the generator. Different input speeds are given to generator for checking its no load performance.



Fig.27. No load test on generator

The drill machine is connected through dimmer to the supply voltage to achieve different speeds. The phase and line voltages are measured for different input speed of prime mover as shown in table 5 below.

Table 5) No load test readings

Sr. No	Speed(N) (rpm)	Output Voltage/ph			Output Voltage/line		
		V _{rn} (V)	V _{yn} (V)	V _{bn} (V)	V _{ry} (V)	V _{yb} (V)	V _{br} (V)
1	75	0.9	0.8	0.8	1	1.1	1.2
2	200	1.7	1.5	1.5	2.5	2.6	2.7
3	300	2.1	1.9	1.9	3.4	3.5	3.8
4	400	2.6	2.5	2.5	4	4.1	4.4
5	550	3.5	3.4	3.4	5.3	5.5	5.9
6	700	4.3	4.2	4.2	6.2	6.4	6.7
7	780	4.9	4.6	4.6	7.1	7.2	7.5

B) Load Test:

In this test the load is connected at the output of the generator. The load requirement is that it should require low voltage and should consume high current. These types of loads available in the laboratory are rheostats. Hence we taken six rheostats of 5 A and 40Ω. In each phase two rheostats are connected in parallel to achieve approximately full load on generator as shown in fig 28a) & b). With the help of drill machine input is given to the generator.

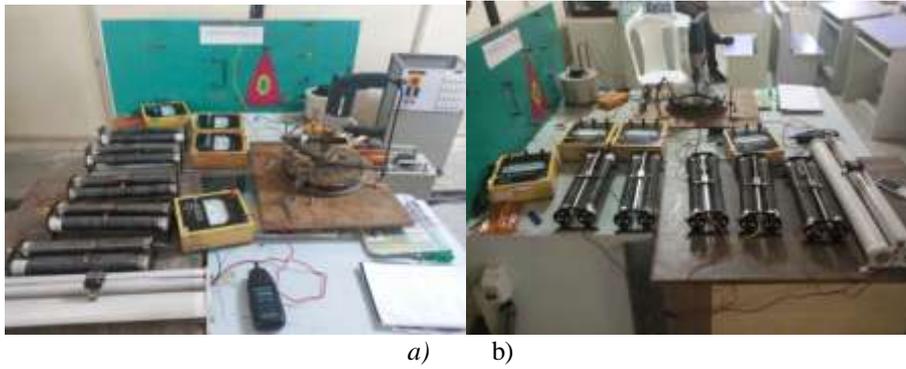


Fig.28 a) Side view of load test b) front view of load test

Three ammeters each of (0-20)A are connected in series with each phase and measure the currents in each phase. Multimeters are used to measure phase and line voltages. Power is measured by using wattmeters of 10A, 50 V. The drill machine is connected through dimmer to the supply voltage to achieve different speeds. The phase and line voltages are measured for different input speed of prime mover as shown in table 6 below.

Table 6) Load test readings

Sr. No	Speed (N) (rpm)	Ir(A)	Iy(A)	Ib(A)	Output Voltage/ph			Output Voltage/line			W1	W2	Total Watts
					Vrn(V)	Vyn(V)	Vbn(V)	Vry(V)	Vyb(V)	Vbr(V)			
1	400	4.4	4.4	4.3	2.23	2.24	2.25	3.6	3.8	3.9	20	10	30
2	500	4.18	4.18	4.1	2.7	2.9	2.94	5	5.08	5.1	23	14	37
3	650	4.23	4.23	3.9	3.4	3.44	3.46	5.8	5.9	6	25	19	44
4	730	3.84	3.84	3.5	4.2	4.3	4.33	7.3	7.4	7.5	28	22	50

II. RESULTS

1) **No- load test results:** following fig 29. Shows the graph between output voltage and speed

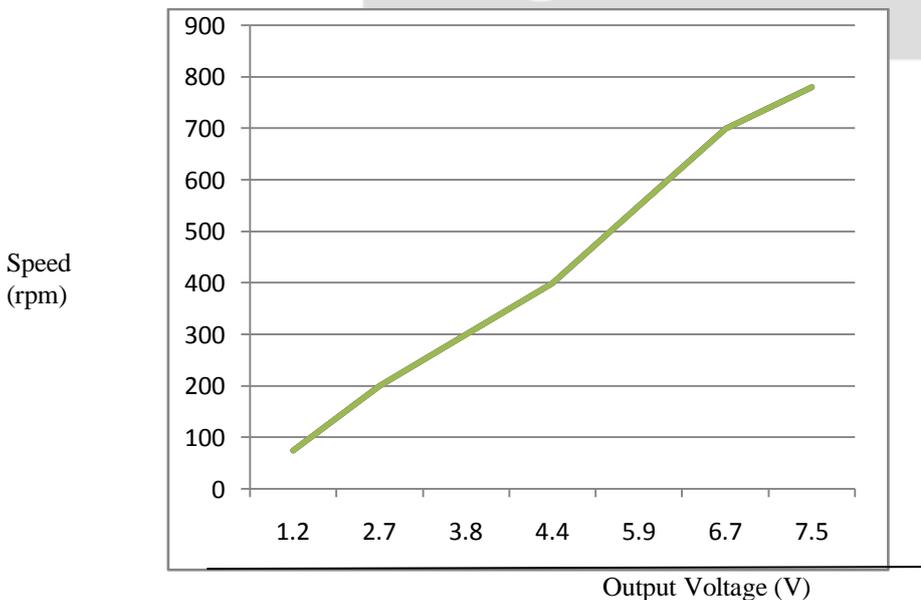


Fig 29. output voltage Vs speed graph

2) Load test results :

Following fig. 30 shows the graph between current and speed

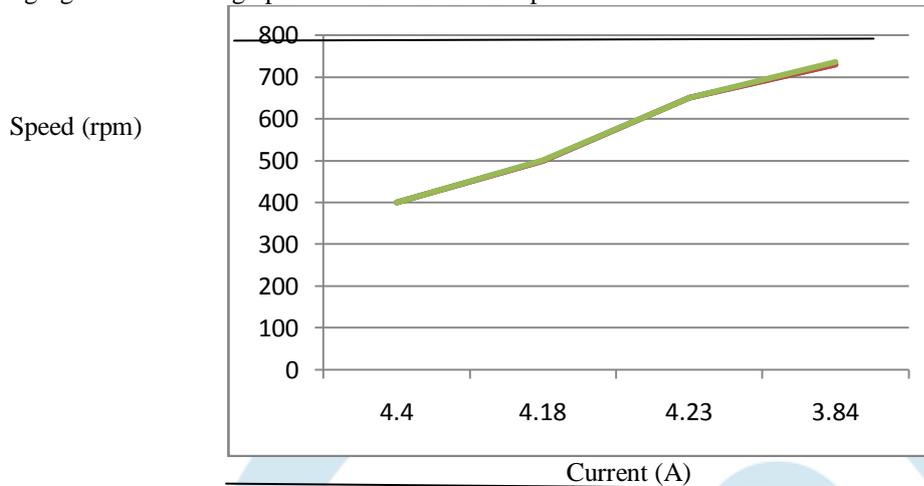


Fig. 30. Current Vs speed

Following fig 31 shows the graph between speed and power

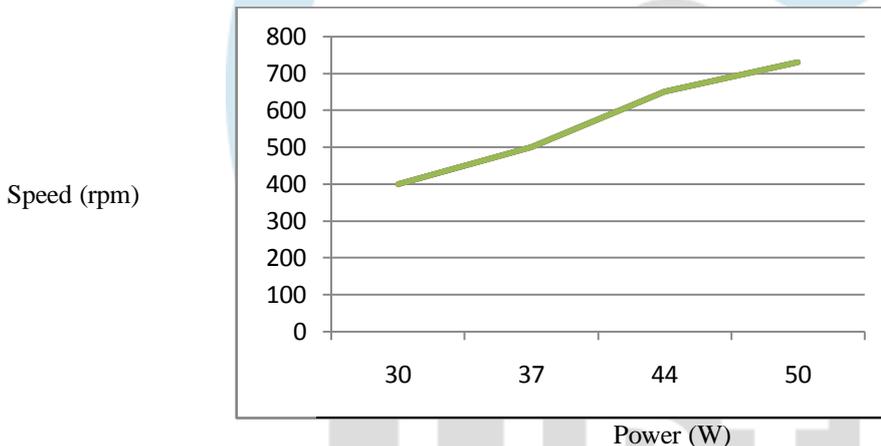


Fig 31. Speed Vs power

I. CONCLUSION

Theoretical design of single stator single rotor AFPM generator is done first with the help of mathematical formulas and then fabricates the generator in the college machine laboratory and workshop with help of electrical and mechanical tools Finally run the generator by prime move at the calculated wind speed in the college laboratory. Conduct two test on generator namely no load test and load test .Draw the observation table and take the readings. After that draw the graph and observe the results.

This project introduced an alternative design procedure for PM generators, Which selects an optimized permutation of design variables based on maximizing the energy yield from the machine. This is indirect contrast to classical design methodology. The practical results obtained by our project are not exactly match perfectly with our theoretical calculations or design. This mismatch is due to the following reasons:

- 1) Due to increase in air gap between rotor and stator because of bad handling.
- 2) Due to imperfection in cutting of circular plates.
- 3) Due to improper pouring of resin, there is no uniform distribution of resin.

II. FUTURE SCOPE

With certain changes this type of generator can be used for electrical energy generation on large scale. The changes are like:

- 1) More development in mechanical design .
- 2) Use of more pure and efficient epoxy resin.
- 3) Addition of one motor rotor magnet disc.
- 4) Use of trapezoidal shaped magnets

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